Honeywell

MICRO SWITCH Force Sensors

Force Sensor

FS Series

FEATURES

- Robust performance characteristics
- Precision force sensing
- Adaptable product design
- Highly reliable
- Signal conditioning available
- Electrically ratiometric output
- Extremely low deflection (30 microns typical @ Full Scale)
- Low repeatability errors (± 0.2% Span)
- Low linearity errors (± 0.5% Span)
- Low off-center loading errors
- Resolution to 1.0 gram force
- · Fast response time
- Low power consumption
- High ESD resistance 10 KV

TYPICAL APPLICATIONS

- Medical infusion pumps
- Kidney dialysis machines
- Robotic end-effectors
- Variable tension control
- Load and compression sensing
- Contact sensing



The FS Series Force Sensor provides precise, reliable force sensing performance in a compact commercial grade package. The sensor features a proven sensing technology that utilizes a specialized piezoresistive micro-machined silicon sensing element. The low power, unamplified, non-compensated Wheatstone bridge circuit design provides inherently stable mV outputs over the 1,500 gram force range.

The force sensor operates on the principle that the resistance of silicon implanted piezoresistors will increase when the resistors flex under an applied force The sensor concentrates force from the application through the stainless steel plunger directly to the silicon sensing element. The amount of resistance changes in proportion to the amount of force being applied. This change in circuit resistance results in a corresponding mV output level.

The sensor package design incorporates a patented modular construction. The use of innovative elastomeric technology and engineered molded plastics results in load capacities of 5.5 Kg overforce. The stainless steel plunger provides excellent mechanical stability and is adaptable to a variety of applications. Various electrical interconnects can accept pre-wired connectors, printed circuit board mounting, and surface mounting. The unique sensor design also provides a variety of mounting options including mounting brackets, as well as application-specific mounting requirements.

MICRO SWITCH Sensing and Control

MICRO SWITCH Force Sensors

Force Sensor

PERFORMANCE CHARACTERISTICS @ 10 ± 0.01 VDC, 25°C

Preliminary, based on limited test data

| Parameter | Min. | Тур. | Max. | Units |
|--|------|-------|------|---------|
| Excitation* | | 10 | 12 | VDC |
| Null shift, 25 to 0°, 25 to 50°C | _ | ± 0.5 | _ | mV |
| Null offset | -30 | 0 | +30 | mV |
| Linearity (BFSL) | _ | ± 0.5 | _ | % Span |
| Sensitivity | _ | 0.24 | _ | mV/grf |
| Sensitivity shift 25 to 0°, 25 to 50°C | | ± 5.0 | | % Span |
| Repeatability | _ | ± 0.2 | _ | % Span |
| Response time | _ | _ | 1.0 | msec |
| Input resistance | _ | 5.0 K | _ | ohms |
| Output resistance | | 5.0 K | | ohms |
| Plunger deflection | | 30 | | microns |
| Weight | | 2.0 | | grams |
| ESD (direct contact - terminals and plunger) | 10 | _ | _ | kVolts |

* Non-compensated force sensors, excited by constant current (1.5 mA) instead of voltage, exhibit partial temperature compensation of Span.

ENVIRONMENTAL SPECIFICATIONS

| Operating temperature | -40 to +85°C (-40 to +185°F) |
|-----------------------|---|
| Storage temperature | -55 to +105°C (-67 to +221°F) |
| Shock | Qualification tested to 150 g |
| Vibration | Qualification tested to 0 to 2 kHz, 20 g sine |
| | |

Note: All force related specifications are established using dead weight or compliant force.

ORDER GUIDE

| | | | ., | Overforce | |
|--------------------|------------------|------|------------------------|-----------|-----------------|
| Catalog Listing | Range (grams) | Min. | <u>Span, m</u> Typ. | V Max. | _ grams Max. |
| FSG-15N1A | 1,500 | 290 | 360 | 430 | 5,500 |

MOUNTING

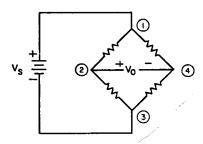
The sensor output characteristics do not change with respect to mounting orientation. Care should be taken not to obstruct the vent hole in the bottom of the sensor housing. Improper venting may result in unstable output.

Mounting bracket mounting torque: 2-5 in. lb. (,21-,56 Nm).

APPLYING FORCE

Evaluation of the sensor is to be performed using dead-weight or compliant force. Application of a rigid, immobile force will result in output drift (decrease) as elastomeric seals relax. Offcenter plunger loading has minimal effect on sensor performance and maintains operation within design specifications.

EXCITATION SCHEMATIC



FS SERIES CIRCUIT

- 1. Circled numbers refer to sensor terminals (pins). Pin 1 is designated with a notch. Pin 1 = Supply V_s (+) Pin 2 = Output, (+) Pin 3 = Ground, (-) Pin 4 = Output, (-)
- 2. The force sensor may be powered by voltage or current. Maximum supply voltage is not to exceed 12 volts. Maximum supply current is not to exceed 1.6 mA. Power is applied across Pin 1 and Pin 3.
- 3. The sensor output should be measured as a differential voltage across Pin 2 and Pin 4 $(V_o = V_2 - V_4)$. The output is ratiometric to the supply voltage. Shifts in supply voltage will cause shifts in output. Neither Pin 2 nor Pin 4 should be tied to ground or voltage supply.

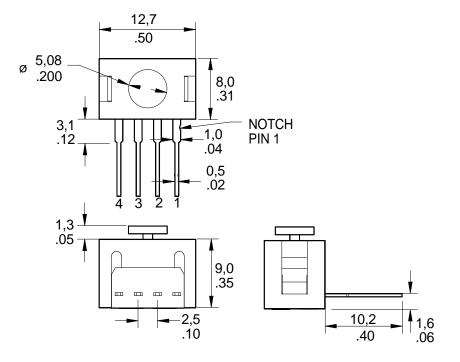
FS Series

MICRO SWITCH Force Sensors

Force Sensor

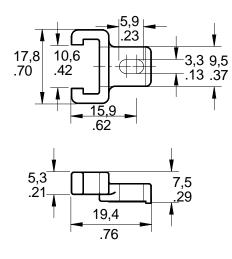
FS Series

MOUNTING DIMENSIONS (for reference only)



ACCESSORY

| Catalog Listing | Description |
|-----------------|--------------------------|
| PC15132 | Plastic mounting bracket |



For application help: call 1-800-537-6945

MICRO SWITCH Force Sensors

Force Sensor



SALES AND SERVICE

Honeywell's MICRO SWITCH Division serves its customers through a worldwide network of sales offices and distributors. For application assistance, current specifications, pricing or name of the nearest Authorized Distributor, contact a nearby sales office. Or call:

1-800-537-6945 USA 1-416-293-8111 Canada 1-815-235-6847 International

INTERNET

http://www.sensing.honeywell.com info@micro.honeywell.com

Specifications may change without notice. The information we supply is believed to be accurate and reliable as of this printing. However, we assume no responsibility for its use.

While we provide application assistance, personally and through our literature, it is up to the customer to determine the suitability of the product in the application.



MICRO SWITCH Honeywell Inc. 11 West Spring Street



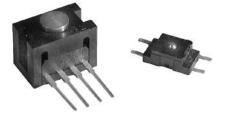
84-08028-0 796 Printed in USA



Helping You Control Your World

Force Sensors FSG and FSL Series

Force



The FS Series Force Sensors provide precise, reliable force sensing performance in a compact commercial grade package. The sensor features a proven sensing technology that utilizes a specialized piezoresistive micro-machined silicon sensing element. The low power, unamplified, noncompensated Wheatstone bridge circuit design provides inherently stable mV outputs over the force range.

FEATURES

- Compact commercial grade package
- Robust performance characteristics
- Adaptable product design
- Precision force sensing
- Electrically ratiometric output
- Extremely low deflection (30 microns typ. @ Full Scale)

Force sensors operate on the principle that the resistance of silicon implanted piezoresistors will increase when the resistors flex under any applied force. The sensor concentrates force from the application, through the stainless steel plunger, directly to the silicon sensing element. The amount of resistance changes in proportion to the amount of force being applied. This change in circuit resistance results in a corresponding mV output level.

- High ESD resistance 10 KV
- Available signal conditioning
- Optional terminal configurations

The sensor package design incorporates a patented modular construction. The use of innovative elastomeric technology and engineered molded plastics results in load capacities of 4.5 Kg over-force. The stainless steel plunger provides excellent mechanical stability and is adaptable to a variety of applications. Various electrical interconnects can accept prewired connectors, printed circuit board mounting, and surface mounting. The unique sensor design also provides a variety of mounting options including mounting brackets, as well as application specific mounting requirements.

TYPICAL APPLICATIONS

- 1. Medical infusion pumps
- 2. Kidney dialysis machines
- 3. Load and compression sensing
- 4. Variable tension control
- 5. Robotic end-effectors
- 6. Wire bonder equipment

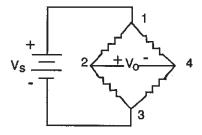
MOUNTING

Sensor output characteristics do not change with respect to mounting orientation. Care should be taken not to obstruct the vent hole in the bottom of the housing. Improper venting may result in unstable output.

APPLYING FORCE

Evaluation of the sensor is to be performed using deadweight or compliant force. Application of a rigid, immobile force will result in output drift (decrease) as elastomeric seals relax. Off-center plunger loading has minimal effect on sensor performance and maintains operation within design specifications.

ELECTRICAL CONNECTIONS



FS SERIES CIRCUIT NOTES

- 1. Circled numbers refer to Sensor Terminals (interface pins). $Pin 1 = V_{s}(+)$
 - Pin 2 = Output, (+)

 - Pin 3 = Ground, (-)Pin 4 = Output, (-)
- 2. The force sensor may be powered by voltage or current. Maximum supply voltage is not to exceed 12 volts. Maximum supply current is not to exceed 1.6 mA. Power is applied across Pin 1 and Pin 3.
- 3. The sensor output should be measured as a differential voltage across Pin 2 and Pin 4 (V_{\circ} = V_{2} - V_{4}). The output is ratiometric to the supply voltage. Shifts in supply voltage will cause shifts in output. Neither Pin 2 nor Pin 4 should be tied to ground or voltage supply.

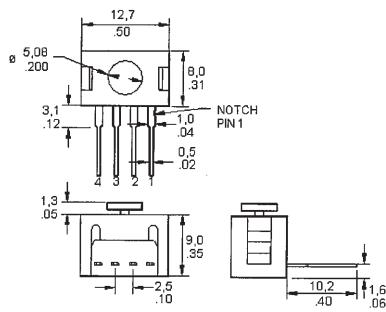


FS Series

FSG and FSL Series

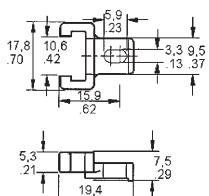
Force Sensors

MOUNTING DIMENSIONS (for reference only) FSG15N1A



ACCESSORY (FSG Sensor only)

PC-15132 Plastic Mounting Bracket



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PERFORMANCE CHARACTERISTICS @ 10.0 ±0.01 VDC, 25°C

| Parameter | Min. | Тур. | Max. | Units |
|--|-------|--------|-------|---------|
| Excitation* | _ | 10.0 | 12.0 | VDC |
| Null offset | -30 | 0 | 30 | mV |
| Operating Force | 0 | _ | 1500 | grams |
| Sensitivity | 0.20 | 0.24 | 0.28 | mV/gram |
| Linearity (B.F.S.L.)** | _ | ±22.5 | 45 | grams |
| Null Shift $+25^{\circ}C$ to $0^{\circ}C$, $+25^{\circ}C$ to $+50^{\circ}C$ | _ | ±1.0 | | mV |
| Sensitivity Shift +25°C to 0°C | _ | 0.012 | _ | mV/gram |
| +25°C to +50°C | — | -0.012 | — | mV/gram |
| Hysteresis | _ | 45 | 180 | grams |
| Repeatability (@ 1500 grams) | _ | 30 | 120 | grams |
| Input Resistance | 4.0 K | 5.0 K | 6.0 K | Ohms |
| Output Resistance | 4.0 K | 5.0 K | 6.0 K | Ohms |
| Overforce | _ | _ | 4,500 | grams |

ENVIRONMENTAL SPECIFICATIONS

| Operating Temperature | -40° to 85°C (-40° to +185°F) |
|------------------------------|---|
| Storage Temperature | -55° to +105°C (-131° to +221°F) |
| Vibration | Qualification tested to 10 Hz to 2 kHz, 20 g sine |
| Shock | Qualification tested to 150 g, 6 ms, half-sine |
| Solderability | 5 sec at 315°C per lead |
| Output ratiometric | Within Supply Range |
| **BESLBest Fit Straight Line | |

B.F.S.L.—Best Fit Straight Line **Note: All force related specifications established using dead weight or compliant force.

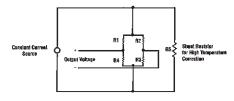
FS SERIES ORDER GUIDE

| Catalog | Force Range | Sensitivity mV/V/gram | | | Span mV | Over Force grams |
|----------|-------------|--------------------------|------|------|-----------------|---------------------|
| Listing | (grams) | Min. | Тур. | Max. | Тур. | Max. |
| FSG15N1A | 1,500 | .02 | .024 | .028 | 360 (at 10 VDC) | 4,500 |

Constant Current Excitation Schematic

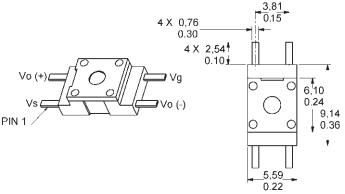
*Non-compensated force sensors, excited by constant current instead of voltage, exhibit temperature compensation of Span. Application Note #1 briefly discusses current excitation.

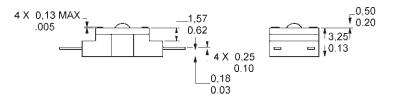
Constant current excitation has an additional benefit of temperature measurement. When driven by a constant current source, a silicon pressure sensor's terminal voltage will rise with increased temperature. The rise in voltage not only compensates the Span, but is also an indication of die temperature.



Force Sensors FSG and FSL Series

MOUNTING DIMENSIONS (for reference only) FSL05N2C





PERFORMANCE CHARACTERISTICS @ 5.0 ±0.01 Excitation, 25°C

| Parameter | Min. | Тур. | Max. | Units |
|---|-------|--------|-------|---------|
| Excitation* | | 5.0 | 12 | VDC |
| Null offset | -15 | 0 | 15 | mV |
| Operating Force | 0 | _ | 500 | grams |
| Sensitivity | 0.1 | 0.12 | 0.14 | mV/gram |
| Linearity (B.F.S.L.)** | _ | ±10 | _ | grams |
| Repeatability @ 300 g | _ | ±10 | _ | grams |
| Null Shift $+25^{\circ}$ C to 2° C, $+25^{\circ}$ C to $+40^{\circ}$ C | _ | ±0.5 | _ | mV |
| Sensitivity Shift +25°C to 2°C | _ | 0.012 | _ | mV/gram |
| +25°C to +40°C | _ | -0.012 | _ | mV/gram |
| Input Resistance | 4.0 K | 5.0 K | 6.0 K | Ohms |
| Output Resistance | 4.0 K | 5.0 K | 6.0 K | Ohms |
| Overforce | | _ | 4,500 | grams |
| ESD (Direct contact, terminals and plunger) | 10 | _ | _ | kVolts |
| | | | | |

ENVIRONMENTAL SPECIFICATIONS

| Operating Temperature | +2°C to +40°C (+36°F to +104°F) |
|-------------------------------|---|
| Storage Temperature | -40° to +70°C (-40° to +158°F) |
| Vibration | Qualification tested to 10 Hz to 2 kHz, 20 g sine |
| Shock | Qualification tested to 150 g, 6 ms, half-sine |
| MCTF | 7 million |
| Solderability | 5 sec at 315°C per lead |
| Output ratiometric | Within Supply Range |
| **PESI Poot Eit Stroight Ling | |

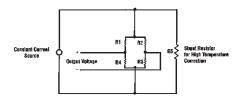
**B.F.S.L.—Best Fit Straight Line Note: All force related specifications established using dead weight or compliant force.

FS SERIES ORDER GUIDE

| Catalog | Force Range | Sensitivity mV/V/gram | | | Span mV | Over Force grams |
|----------|-------------|--------------------------|------|------|---------------|---------------------|
| Listing | (grams) | Min. | Тур. | Max. | Тур. | Max. |
| FSL05N2C | 500 | .02 | .024 | .028 | 60 (at 5 VDC) | 4,500 |

Constant Current Excitation Schematic *Non-compensated force sensors, excited by constant current instead of voltage, exhibit temperature compensation of Span. Application Note #1 briefly discusses current excitation.

Constant current excitation has an additional benefit of temperature measurement. When driven by a constant current source, a silicon pressure sensor's terminal voltage will rise with increased temperature. The rise in voltage not only compensates the Span, but is also an indication of die temperature.



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Horosoft USA
H 1-815-235-6847 International
Horosoft USA
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Honeywell

Model 1865 Series Force/Pressure transducer



DESCRIPTION

The Model 1865 is a high-performance transducer specifically designed to address the needs of medical and specialized OEM applications. Offering laser-trimmed compensation, the Model 1865 may be specified to operate with either a constant current or voltage supply.

The Model 1865 employs a solid state piezoresistive pressure transducer mounted in a plastic package. For applications where force is applied by a flexible membrane to the sensor, such as found in infusion pumps, the Model 1865's precision height silicone diaphragm provides long life and is a reliable replacement for older force or load cell transducers. Utilizing a silicon rubber diaphragm, the 1865 is compatible with some liquid media applications.

The Model 1865 provides access to important safety features in critical care medical instrumentation, such as occlusion pressure or infiltration detection. The pressure data can provide medical personnel with useful diagnostic information regarding the condition of the patient's circulatory system. These force/pressure transducers can also be used with other medical dispensing devices, such as syringe pumps, to improve safety and accuracy.

May be operated in either current or voltage excitation, the Model 1865's output can be amplified or signal conditioned, as required. The semiconductor-based sensor offers high resolution using its Wheatstone Bridge strain gauge design. The height of the unit's patented, poured-in-place silicon rubber diaphragm is controlled to ensure sensitivity to low pressure. This diaphragm is bonded to a plastic header and transmits force applied through a special silicone gel to the diaphragm of a silicon peizoresistive die. The back of the die is exposed to atmospheric pressure, which results in a gauge pressure output.

FEATURES

- Silicon pressure/force interface diaphragm
- Force measurement for infusion pump applications
- Pressure measurement for liquid media
- Medical-grade materials
- 8-pin DIP electrical connection
- Laser trimmed
- Choice of voltage or constant current excitation

TYPICAL APPLICATIONS

- Infusion pumps
- Anesthesia monitors
- Non-corrosive, nonpressurized media-level sensors
- · Ventilation systems
- Blood pressure equipment
- Syringe pumps
- Drug delivery systems

Model 1865 Series

ELECTRICAL SPECIFICATIONS

| | Ratings |
|-----------------------------|--------------------------------|
| Input impedance | |
| Current excitation | 2.0 kOhm min. to 8.0 kOhm max. |
| Voltage excitation | 8.0 kOhm min. to 40 kOhm max. |
| Output impedance | |
| Current excitation | 3.5 kOhm min. to 6.0 kOhm max. |
| Voltage excitation | 3.5 kOhm min. to 6.0 kOhm max. |
| Input excitation | |
| Current | < 2.0 mA |
| Voltage | < 15.0 Vdc |
| Effect of excitation change | Ratiometric |
| Response time (10% to 90%) | \leq 5 milliseconds |
| Insulation resistance | ≥ 100 MOhm at 50 Vdc |
| Output common mode voltage | 50 % of input typical |

PHYSICAL SPECIFICATIONS

| | Specification |
|--------------------------------|-------------------------------|
| Pressure over-range protection | 3X span or 60 psi, whichever |
| | is least |
| Media/materials compatibility | |
| Top side | Room atmosphere, directly |
| | applied force, and liquids |
| | compatible with dimethyl |
| | silicon, polyetherimide |
| | (Ultem) |
| Bottom side | Non-corrosive dry gasses |
| | and fluids compatible with |
| | silicon, Pyrex, RTV silicone, |
| | and ceramic |
| Mass | 3.0 g with laser-trim board |

ENVIRONMENTAL CONDITIONS

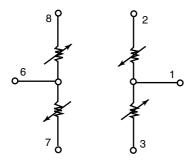
| | Specification |
|------------------|-------------------------------------|
| Position effect | \leq 0.05 % of zero or span shift |
| | for 90° tilt in any direction |
| Vibration effect | No change in performance at |
| | 10 Gs RMS, 20 Hz to |
| | 2,000 Hz |
| Shock | 100 Gs for 11 milliseconds |
| Life | 1 million cycles |

PERFORMANCE SPECIFICATIONS

| | Min. | Тур. | Max. | Unit | |
|-----------------------------------|----------|----------------------------------|---------------|---|--|
| Temperature Compensated Performan | nce | | | | |
| Nonlinearity | - | 0.10 | 0.25 | % of Span, BFSL | |
| Hysteresis | - | 0.0125 | 0.015 | % of Span, BFSL | |
| Repeatability | - | 0.0125 | 0.015 | % of Span, BFSL | |
| Output (laser trimmed normalized) | | | | | |
| Current excitation | 98 | 100 | 102 | mVdc | |
| Voltage Excitation | 38 | 40 | 42 | mVdc | |
| Zero pressure | -2 | 0 | 2 | mVdc | |
| Temperature Performance | I | | | 1 | |
| Compensated temperature range | -1 °C to | -1 °C to 54 °C [30 °F to 129 °F] | | | |
| Operating temperature range | -28 °C | to 54 °C [-19 ° | °F to 129 °F] | | |
| Maximum zero error | | | 0.5 | % of Span in reference to 27 °C [80.6 °F] | |
| Maximum span error | | | 0.5 | % of Span in reference to 27 °C [80.6 °F] | |
| Thermal hysteresis | | | 0.2 | % of Span, compensated temperature range | |
| Long-term stability | | | ± 0.3 | % of Span per six months | |

Force/Pressure transducer

FIGURE 1. SENSING ELEMENTS

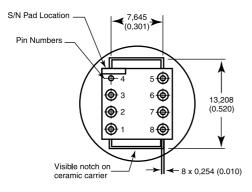


| Pin | Connection | Pin | Connection |
|-----|------------|-----|------------|
| 1 | + Output | 5 | + Input |
| 2 | NC | 6 | - Output |
| 3 | - Input | 7 | NC |
| 4 | NC | 8 | NC |

REFERENCE CONDITIONS

| | Specification |
|---------------------|---|
| Media temperature | 27 °C ± 1 °C [80 °F ± 2 °F] |
| Ambient temperature | 27 °C ± 1 °C [80 °F ± 2 °F] |
| Vibration | 0.1 G (1 m/s/s) max. |
| Humidity | 50 % ± 10 % |
| Ambient pressure | 12.8 psi to 16.5 psi |
| | [860 mBar to 1060 mBar] |
| Excitation source | 1.5 mAdc ± 0.0015 mAdc or |
| | $10.0 \text{ Vdc} \pm 0.01 \text{ Vdc}$ |

FIGURE 2. MOUNTING DIMENSIONS IN MM (INCHES), FOR REFERENCE ONLY



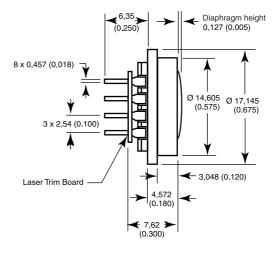


FIGURE 3. LASER TRIM BOARD

Current Excitation, Normalized Output

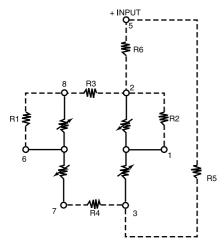
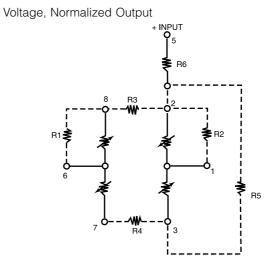
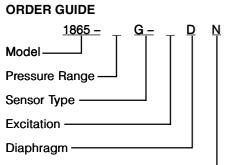


FIGURE 4. LASER TRIM BOARD



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Compensation -

PRESSURE RANGE

01 = 0 psi to 5 psi 02 = 0 psi to 10 psi 03 = 0 psi to 15 psi 05 = 0 psi to 25 psi 07 = 0 psi to 30 psi

SENSOR TYPE

G = Gauge Pressure

EXCITATION

L = 1.5 mA K = 10 Vdc

DIAPHRAGM TYPE

D = Dimethyl Silicone

COMPENSATION

N = Laser trimmed, normalized output

ACCURACY GRADE

Higher accuracy grades are available as specials.

Custom configurations are available on request.

Automation and Control Solutions

Sensing and Control Honeywell 11 West Spring Street Freeport, Illinois 61032, USA www.honeywell.com

WARRANTY/REMEDY

Honeywell warrants goods of its manufacture as being free of defective materials and faulty workmanship. Honeywell's standard product warranty applies unless agreed to otherwise by Honeywell in writing; please refer to your order acknowledgement or consult your local sales office for specific warranty details. If warranted goods are returned to Honeywell during the period of coverage, Honeywell will repair or replace, at its option, without charge those items it finds defective. The foregoing is buyer's sole remedy and is in lieu of all warranties, expressed or implied, including those of merchantability and fitness for a particular purpose. In no event shall Honeywell be liable for consequential, special, or indirect damages.

While we provide application assistance personally, through our literature and the Honeywell web site, it is up to the customer to determine the suitability of the product in the application.

Specifications may change without notice. The information we supply is believed to be accurate and reliable as of this printing. However, we assume no responsibility for its use.

WARNING PERSONAL INJURY

DO NOT USE these products as safety or emergency stop devices or in any other application where failure of the product could result in personal injury.

Failure to comply with these instructions could result in death or serious injury.

SALES AND SERVICE

Honeywell serves its customers through a worldwide network of sales offices, representatives and distributors. For application assistance, current specifications, pricing or name of the nearest Authorized Distributor, contact your local sales office or:

E-mail: info.sc@honeywell.com

Internet: www.honeywell.com/sensing

Phone and Fax:

| Asia Pacific | +65 6355-2828 |
|---------------|-------------------------|
| | +65 6445-3033 Fax |
| Europe | +44 (0) 1698 481481 |
| | +44 (0) 1698 481676 Fax |
| Latin America | +1-305-805-8188 |
| | +1-305-883-8257 Fax |
| USA/Canada | +1-800-537-6945 |
| | +1-815-235-6847 |
| | +1-815-235-6545 Fax |
| | |

WARNING MISUSE OF DOCUMENTATION

- The information presented in this product sheet is for reference only.
 Do not use this document as a product installation guide.
- Complete installation, operation, and maintenance information is provided in the instructions supplied with each product.

Failure to comply with these instructions could result in death or serious injury.



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Honeywell

Pressure Sensors

FS01/FS03 Force Sensors

FS Series

FEATURES

- 0 to 1.5 pounds and 0 to 3.0 pound ranges
- High-level output range
- Temperature compensated
- Calibrated zero and span
- Small size
- Low noise

TYPICAL APPLICATIONS

- Medical infusion pumps
- Ambulatory noninvasive
 pump pressure
- Occulsion detection
- Kidney dialysis machines
- Load and compression
 sensing
- Variable tensions control



The FS01/FS03 sensors are special low cost, peizoresistive-based force sensors. These high-level voltage output, calibrated, and temperature compensated sensors give an accurate and stable output over a 5 °C to 50 °C [41 °F to 122 °F] temperature range. They offer simple operation from a single 5.0 Vdc supply. Operation from any DC supply voltage, up to 12.0 Vdc, is acceptable.

The FS01/FS03 sensors feature an integrated circuit sensor element and laser trimmed think film ceramic in a small plastic housing. Their extremely small size enables the use of multiple sensors in limited available space. This package also provides excellent corrosion resistance and isolation to external package stress.

WARNING

PERSONAL INJURY DO NOT USE these products as safety or emergency stop devices or in any other application where failure of the product could result in personal injury.

Failure to comply with these instructions could result in death or serious injury.

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Sensing and Control

Pressure Sensors FS01/FS03 Force Sensors



PRESSURE SENSOR SPECIFICATIONS

| | Max. Ratings |
|---|-----------------|
| Supply voltage, Vs | 12.0 Vdc |
| Maximum over load | 3.18 kg [7 lbs] |
| Lead temperature (soldering 2-4 seconds) | 220 °C [428 °F] |

| ENVIRUNIVIENTAL SPECIFICATIONS | | |
|--------------------------------|--------------------------------------|--|
| Compensated temperature | 5 °C to 50 °C [41 °F to 122 °F] | |
| Operating temperature | 0 °C to 70 °C [0 °F to 158 °F] | |
| Storage temperature | -20 °C to 85 °C [13 °F to 185 °F] | |
| Humidity limits | 0% RH to 95% RH | |

ENIVIDONMENTAL SPECIFICATIONS

STANDARD FORCE RANGES

| | | | Full-Scale Span | | |
|-------------|--|---------------|-----------------|---------|----------|
| Part Number | Operating Force | Maximum Force | Min. | Тур. | Max. |
| FS01 | 0 lbs to 1.5 lbs [0 kg to 0.68 kg] | 7 lbs | 2.85 Vdc | 3.0 Vdc | 3.15 Vdc |
| FS03 | 0 lbs to 3.0 lbs [0 kg to 1.36 kg] | 7 lbs | 2.85 Vdc | 3.0 Vdc | 3.15 Vdc |

PERFORMANCE SPECIFICATIONS

| | Min. | Тур. | Max. | Unit |
|---|------|-------|-------|------|
| Zero force offset | 0.95 | 1.0 | 1.05 | Vdc |
| Full scale span ⁽²⁾ | 2.85 | 3.0 | 3.15 | Vdc |
| Linearity | _ | ± 1.0 | ± 3.0 | %FSS |
| Hysteresis (3) | - | ± 0.5 | _ | %FSS |
| Temp effect on Span (0 °C to 50 °C [0 °F to 122 °F]) $^{\scriptscriptstyle (4)}$ | _ | ± 1.0 | ± 2.5 | %FSS |
| Temp. effect on Offset (0 °C to 50 °C [0 °F to 122 °F]) $^{\scriptscriptstyle (4)}$ | _ | ± 1.0 | ± 2.5 | %FSS |
| Creep ⁽⁵⁾ | - | 0.5 | _ | %FSS |
| Long-term stability of Offset and Span ⁽⁶⁾ | - | ± 1.0 | _ | %FSS |

Specification Notes:

Note 1: Reference conditions (unless otherwise noted): Supply voltage, Vs = 5 Vdc; T_A = 25 °C [77 °F]

Note 2: Full-scale Span is the algebraic difference between the output voltage at full-scale load and the output at zero load. Span is ratiometric to the supply voltage.

Note 3: Hysteresis is the maximum output difference at any point within the operating pressure range for increasing and decreasing load.

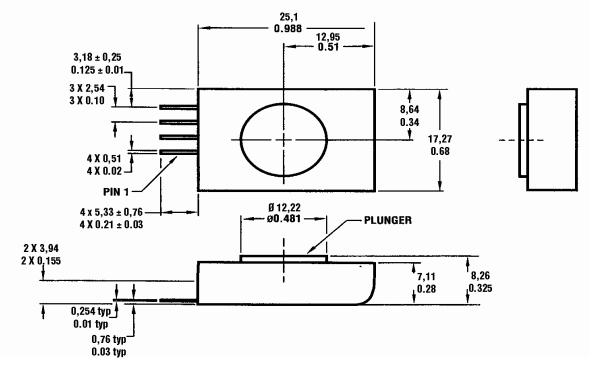
- Note 4: Maximum error band of the offset voltage and the effort band of span, relative to the 25 °C [77 °F] reading.
- Note 5: Maximum difference in output at full-scale load in a 20 minute period.
- Note 6: Maximum difference in output within any operating force after 1 million force cycles

Pressure Sensors

FS01/FS03 Force Sensors

FS Series

DIMENSIONAL DRAWING (FOR REFERENCE ONLY)

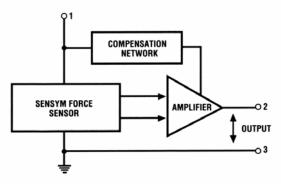


Tolerances, unless otherwise noted

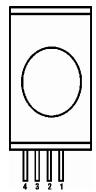
± 0.01 for two decimal places

± 0.005 for three decimal places

EQUIVALENT CIRCUIT



ELECTRICAL CONNECTION PINOUT



Pin 1 = + Supply Pin 2 = + Output Pin 3 = - Output/Ground Pin 4 = N/C

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ORDER GUIDE

| Part Number | Force Range |
|-------------|--------------------|
| FS01 | 0 lbs to 1.5 lbs |
| | [0 kg to 0.68 kg] |
| FS03 | 0 lbs to 3.0 lbs |
| | [0 kg to 1.36 kg] |

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INTERNET

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Honeywell

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FS Series

Force Sensors FSS Low Profile Force Sensors

FS Series

FEATURES

- True Surface Mount Technology
- Maximum peak reflow temperature of 260 °C [500 °F]
- Compact, commercial grade package
- Robust performance characteristics
- Adaptable package design
- Precision force sensing
- Reliability rated at 20 million MCTF at 25 °C [77 °F]
- Electrically ratiometric
 output
- Extremely low deflection (30 microns typ. @ Full Scale)
- High ESD resistance 8 kV
- Available signal conditioning
- Optional terminal configurations

TYPICAL APPLICATIONS

- Medical infusion pumps
- Ambulatory noninvasive pump pressure
- Occlusion detection
- Kidney dialysis machines
- Load and compression sensing
- Variable tensions control
- Robotic end-effectors
- Wire bonding equipment

PERSONAL INJURY

DO NOT USE these products as safety or emergency stop devices or in any other application where failure of the product could result in personal injury.

Failure to comply with these instructions could result in death or serious injury.



The FS Series sensors provide precise reliable force sensing performance in a compact commercial grade package at a cost effective price. The sensor features a proven sensing technology that uses a specialized piezoresistive micromachined silicon sensing element. The low power, unamplified, uncompensated Wheatstone bridge circuit design provides inherently stable mV outputs over the force range.

Force sensors operate on the principle that the resistance of siliconimplanted piezoresistors will increase when the resistors flex under any applied force. The sensor concentrates force from the applications, through the stainless steel ball, directly to the silicon-sensing element. The amount of resistance changes in proportion to the amount of force being applied. This change in circuit resistance results in a corresponding mV output level change.

The sensor package design incorporates patented modular construction. The use of innovative elastomeric technology and engineered molded plastics result in load excitation capacities of 4.5/5.5 kg over-force. The stainless steel ball provides excellent mechanical stability and is adaptable to a variety of applications. The FSS sensor delivered 20 million operations in Mean Cycles to Failure (MCTF) reliability testing at 50 °C [122 °F]. This test determines the number of possible sensor operations at full scale until failure. Various electric interconnects can accept prewired connectors, printed circuit board mounting, and surface mountings. The unique sensor design also provides a variety of mounting options that include mounting brackets, as well as application specific mounting requirements.

A WARNING

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Sensing and Control

Force Sensors FSS Low Profile Force Sensors

FS Series

PERFORMANCE CHARACTERISTICS @ 5.0 \pm 0.01 Vdc Excitation*, 25 °C [77 °F]

| | <u> </u> | | | <u> </u> |
|---|----------|---------|-------|----------|
| Parameter | Min. | Typical | Max. | Units |
| Null Offset | -15 | 0 | +15 | mV |
| Operating Force | 0 | - | 1500 | grams |
| Sensitivity. | 0.1 | 0.12 | 14 | mV/gram |
| Linearity (B.FS.L.)** | - | ± 1.5 | - | % span |
| Repeatability @ 300 g | - | ± 10 | - | grams |
| Null Shift | _ | | | |
| 25 °C to 2 °C [77 °F to 35.6 °F] | - | ± 0.5 | _ | mV |
| 25 °C to 40 °C [77 °F to 104 °F] | - | ± 0.5 | - | mV |
| Sensitivity Shift | | | | |
| 25 °C to 50 °C [77 °F to 122 °F] | - | 5.5 | - | % span |
| 25 °C to 0 °C [77 °F to 32 °F] | - | 5.5 | - | % span |
| Input Resistance | 4.0 K | 5.0 K | 6.0 K | Ohms |
| Output Resistance | 4.0 K | 5.0 K | 6.0 K | Ohms |
| Overforce | - | - | 4,500 | grams |
| ESD (direct contact, terminals and plunger) | 8 | _ | _ | kV |
| | | | | |

* Non-compensated force sensors, excited by constant current (1.5 mA) instead of voltage, exhibit partial temperature compensation of Span.

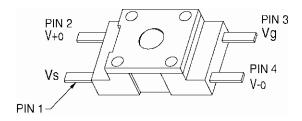
** BFSL: Best Fit Straight Line

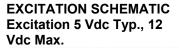
ENVIRONMENTAL SPECIFICATIONS

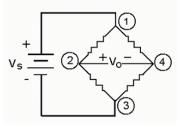
| Operating temperature | -40 °C to 85 °C [-40 °F to 185 °F] |
|-----------------------|---|
| Storage temperature | -40 °C to 100 °C [-40°F to 212 °F] |
| Shock | Qualification tested to 150 g |
| Vibration | Qualification tested to 0 to 2 kHz, 20 g sine |
| MCTF | 20 million at 25 °C [77 °F] |
| Solderability | 5 sec at 315 °C [599 °F] per lead |
| Output ratiometric | Within supply range |
| | |

Note: All force related specifications are established using dead weight or compliant force.

SENSOR PINOUT







FS SERIES CIRCUIT

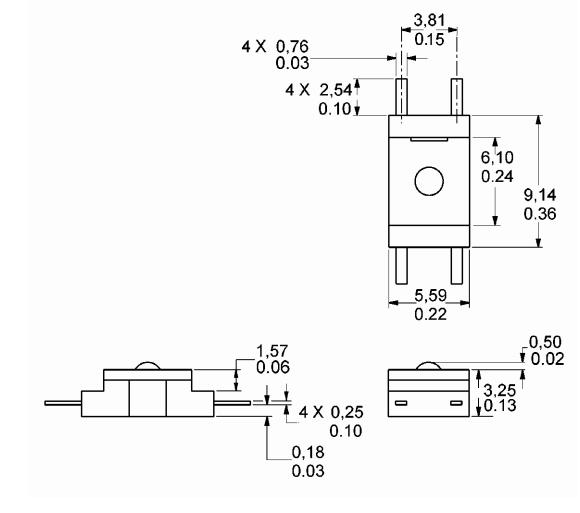
- Circled numbers refer to sensor terminals (pins).
 Pin 1 = Supply V_S (+)
 Pin 2 = Output Vo (+)
 Pin 3 = Ground Vg (-)
 Pin 4 = Output Vo (-)
- The force sensor may be powered by voltage or current. Maximum supply voltage is not to exceed 12 volts. Maximum supply current is not to exceed 1.6 mA. Power is applied across Pin 1 and Pin 3.
- The sensor output should be measured as a differential voltage across Pin 2 and Pin 4 (Vo = V₂ -V₄). The output is ratiometric to the supply voltage. Shifts in supply voltage will cause shifts in output. Neither Pin 2 nor Pin 4 should be tied to ground or voltage supply.

Force Sensors

FSS Low Profile Force Sensors

FS Series

MOUNTING DIMENSIONS (for reference only) mm/in



| DESCRIPTION |
|-------------|
|-------------|

| Packing Style |
|---------------|
| Tube |
| Bubble Pack |
| Tape and Reel |
| |

Force Sensors FSS Low Profile Force Sensors



WARRANTY/REMEDY

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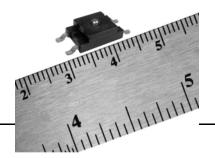
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FSS-SMT Series Low Profile Force Sensor



DESCRIPTION

Honeywell's FSS-SMT Series force sensors are designed to be one of the most reliable force sensors available as illustrated by 20 million Mean Cycles To Failure (MCTF) at 25 °C [77 °F] rating. This low profile Surface Mount Technology (SMT) sensor allows for automated assembly on a printed circuit board, often helping the customer to reduce assembly costs.

The FSS-SMT Series force sensor is designed to provide precise and reliable force sensing performance in a compact commercial-grade package. The sensor incorporates Honeywell sensing technology that uses a specialized piezoresistive micromachined silicon sensing element. The low power, unamplified, uncompensated Wheatstone bridge circuit design provides inherently stable millivolt output over the force range. Force sensors operate on the principle that the resistance of silicon-implanted piezoresistors will change when the resistors flex under applied force. The sensor concentrates force from the applications, through the stainless steel ball, directly to the silicon-sensing element. The amount of resistance changes in proportion to the amount of force being applied. This change in circuit resistance results in a corresponding mV output level change.

The sensor package design incorporates patented modular construction. The use of innovative elastomeric technology and engineered molded plastics results in load excitation capacities of 44 N over-force. The stainless steel ball provides excellent mechanical stability, and is suitable for a variety of potential medical and commercial applications.

FEATURES/BENEFITS

- Surface Mount Technology allows for automated assembly and may eliminate hand soldering
- RoHS-compliant materials meet Directive 2002/95/EC
- Low deflection (30 microns typical at full scale) help reduce measurement error
- Direct mechanical coupling of the actuation ball to the sense element reduces coupling errors and keeps mechanical hysteresis to a minimum
- Product rating of 20 million MCTF at 25 °C [77 °F], subject to application variation, provides for consistent output over time and reduces repairs or replacements
- Small size minimizes space on the printed circuit board (PCB)
- Provides enhanced sensitivity without compromising signal integrity, resulting in low system noise and reducing measurement errors
- Electrically ratiometric output accommodates supply voltage variations, leading to low ratiometricity error
- Low voltage supply allows for use in many battery powered applications
- High resistance to electrostatic discharge (ESD) (8 KV) meets ESD Sensitivity Classification Level 3, reducing special handling during assembly
- · Sensor output has low sensitivity to many mounting stresses

FSS-SMT Series

POTENTIAL APPLICATIONS

Medical

- Infusion pumps
- Ambulatory non-invasive pumps
- Occlusion detection
- Kidney dialysis machines
- Enteral pumps

Commercial

- Load and compression sensing
- Variable tension control
- Wire bonding equipment

Table 1. Absolute Maximum Ratings¹

| Parameter | Min. | Max. | Unit |
|----------------------------------|-----------|--------------------|---------|
| Electro-Static Discharge (ESD) | - | 8 | kV |
| Storage temperature ² | -40 [-40] | 100 [212] | °C [°F] |
| Solderability ³ | - | 260 [500] for 10 s | °C [°F] |

Table 2. Operating Specifications (Performance characteristics at 5.0 ± 0.01 Vdc excitation, 25 °C [77 °F])

| Parameter | Min. | Typical | Max. | Unit |
|---|-----------|---------|----------|---------|
| Supply voltage ^₄ | 3.0 | 5.0 | 6.0 | V |
| Operating force | 0 | - | 14.7 | N |
| Operating temperature ⁵ | -40 [-40] | - | 85 [185] | °C [°F] |
| Offset ⁶ | -15 | 0 | 15 | mV |
| Span ⁷ | 150 | 180 | 210 | mV |
| Sensitivity [®] | 10.2 | 12.2 | 14.3 | mV/N |
| Force non-linearity (BFSL) ⁹ | - | ±0.7 | ±1.5 | %FSS |
| Repeatability at 2.9 N ¹⁰ | - | ±1.5 | - | mV |
| Mechanical hysteresis ¹¹ | | ±0.5 | | %FSS |
| Thermal effect on offset ¹² | | | | |
| 25 °C to 0 °C [77 °F to 32 °F], | - | ±0.5 | - | mV |
| 25 °C to 50 °C [77 °F to 122 °F] | | | | |
| Thermal effect on span ¹³ | | | | |
| 25 °C to 0 °C [77 °F to 32 °F], | - | ±5.5 | - | %FSS |
| 25 °C to 50 °C [77 °F to 122 °F] | | | | |
| Input resistance | 4.0 | 5.0 | 6.0 | kOhm |
| Output resistance | 4.0 | 5.0 | 6.0 | kOhm |
| Over force ¹⁴ | 44 | - | - | N |

Low Profile Force Sensor

Table 3. Environmental Specifications

| Parameter | Characteristics |
|---|---|
| Shock | Qualification tested to 150 G |
| Vibration | Qualification tested to 0 to 2 kHz, 20 G sine |
| Mean Cycles To Failure (MCTF) ¹⁵ | 20 million at 25 ° C [77 ° F] |

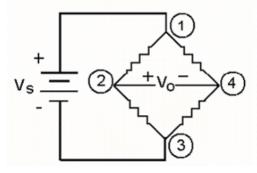
Notes:

- 1. Absolute maximum ratings are the extreme limits that the device can withstand without damage to the device.
- The temperature range over which the product may safely be exposed without excitation or force applied. Under these
 conditions the product will remain in specification after excursion to any temperatures in this range. Exposure to temperatures
 beyond this range may cause permanent damage to the product.
- 3. The maximum temperature and time for which the product can be exposed to for processing of solder electrical connections.
- 4. The range of voltage excitation which can be supplied to the product to produce an output which is proportional to Force but due to Ratiometricity errors may not remain within the specified performance limits.
- 5. The temperature range over which the product will produce an output proportional to force but may not remain within the specified performance limits.
- 6. The output signal obtained when the zero force is applied to the sensor. Also known as "null" or "zero".
- 7. The algebraic difference between output signal measured at the upper and lower limits of the Operating Force Range. Also known as "full scale output" or simply "span".
- 8. The ratio of output signal change to the corresponding input force change. Sensitivity is determined by computing the ratio of Span to the specified Operating Force Range.
- 9. Force Non-Linearity (Best Fit Straight Line): The maximum deviation of product output from a straight line fitted to output measured over the operating force range. The straight line through a set of points which minimizes the sum of the square of the deviations of each of the points from the straight line.
- 10. The maximum difference between output readings when the same force is applied consecutively, under the same operating conditions, with force approaching from the same direction within the operating force range.
- 11. The maximum difference between output readings when the same force is applied consecutively, under the same operating conditions, with force approaching from opposite directions within the operating force range.
- 12. The maximum deviation in Offset due to changes in temperature over the Operating Temperature Range, relative to Offset measured at 25 °C.
- 13. The maximum deviation in Full Scale Span due to changes in temperature over the Operating Temperature Range, relative to Full Scale Span measured at 25 °C.
- 14. The maximum force which may safely be applied to the product for it to remain in specification once force is returned to the Operating Force Range. Exposure to higher forces may cause permanent damage to the product. Unless otherwise specified this applies to all temperature within the Operating Temperature Range.
- 15. MCTF is a basic measure of reliability for a non-repairable device. It is the mean number of cycles to maximum operating force over which a sensor can be expected to operate until failure. The mean value is determined statistically from a probability distribution for failures based upon test data. MCTF may vary depending on the specific application in which a sensor is utilized.

Figure 1. Sensor Pinout



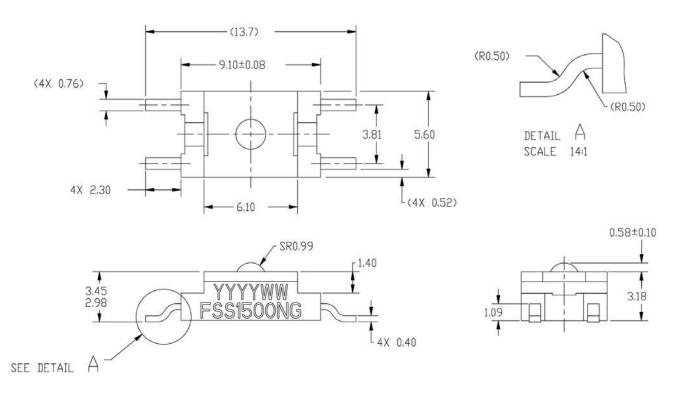
Figure 2. Excitation Schematics – Excitation 5 Vdc Typ., 6 Vdc max.



FS Series Circuit

- 1. Circled numbers refer to sensor terminals (pins).
 - Pin 1 = Supply Vs (+)
 - Pin 2 = Output Vo (+)
 - Pin 3 = Ground Vg (-)
 - Pin 4 = Output Vo (-)
- 2. The force sensor may be powered by voltage or current. Maximum supply voltage is not to exceed 6 V. Maximum supply current is not to exceed 1.2 mA. Power is applied across Pin 1 and Pin 3.
- 3. The sensor output should be measured as a differential voltage across Pin 2 and Pin 4 (Vo=Vo(+)-Vo(-)). The output is ratiometric to the supply voltage. Shifts in supply voltage will cause shifts in output. Neither Pin 2 nor Pin 4 should be tied to ground or voltage supply.

Figure 3. Mounting Dimensions (for reference only) in mm



4 www.honeywell.com/sensing

Low Profile Force Sensor

Figure 4. Suggested Land Pattern in mm

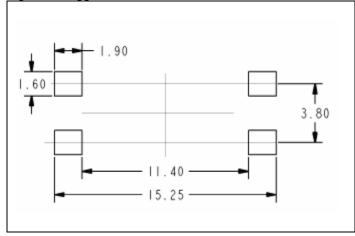


Table 4. Order Guide

| Catalog Listing | Packaging* |
|-----------------|-----------------------------|
| FSS1500NGT | Tube |
| FSS1500NGR | Tape and reel (1,000 units) |

* Tape and reel packaging in development

🛦 WARNING

PERSONAL INJURY

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Internet: www.honeywell.com/sensing

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| | +65 6445-3033 Fax |
| Europe | +44 (0) 1698 481481 |
| | +44 (0) 1698 481676 Fax |
| Latin America | a +1-305-805-8188 |
| | +1-305-883-8257 Fax |
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